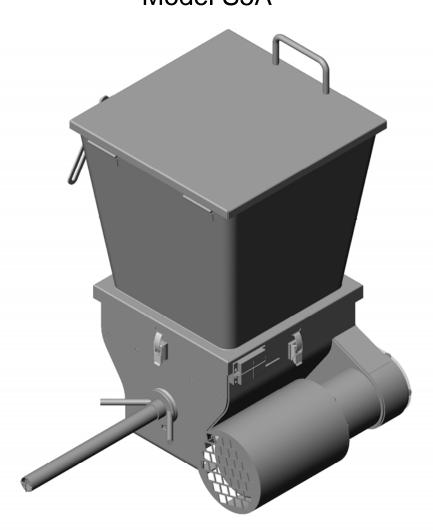


# Installation, Operation and Maintenance Manual for Tecweigh® Volumetric Feeders Model S5A



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Model: \_\_\_\_\_Serial Number: \_\_\_\_

Manual Part Number: 20920003 Ver 1.2 April 2008

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0.00	the Tecweigh Volumetric Feeder.
3.00	Operation, Calibration and Maintenance  The general operation procedures are outlined in this section. This includes basic start-up, shutdown, calibration and feed rate control. Disassembly for cleaning and reassembly is also well documented.
4.00	SCR/PWM Controller Adjustments
	This section provides basic information regarding the SCR or PWM speed control board(s).
5.00	Troubleshooting
	This section describes general problems, causes, and solutions for your feeder.
6.00	Technical Data
	This section is dedicated to listing the standard features, and components of the feeder. Also furnished is a complete listing of available construction types, and standard fabrication methods.
7.00	Addendums & Parts Lists
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	For your information the following are included: Standard and optional controls, Standard Control Enclosure Drawing, Standard Control Schematic, special control system summaries, and schematics specific to your individual feeder system.
9.00	CE Compliance
	For information regarding CE Compliance

# Section 1.00

### Safety



This symbol is intended to alert the user to the presence of important operating and maintenance (servicing) instructions in the literature accompanying the product.



This symbol is intended to alert the user of the presence of uninsulated dangerous voltage within the product's enclosure that may be of sufficient magnitude to constitute a risk of electric shock.



This symbol is intended to alert the user that moving parts can cut or crush. Keep hands clear. Lockout/tagout before servicing



You are urged to study this manual carefully. Please read the safety instructions and warnings. Failure to heed these warnings and instructions could result in serious personal injury or death.

- 1.02 The feeder is provided with safety labels. Replace any that are not legible. Do not paint over labels. The decals shown above and below can be ordered like any other replacement part. Apply labels to the equipment in a location that will be noticed by the operator.
- 1.03 The feeder includes four threaded mounts on the feeder's bottom. The mounts are threaded so bolts can be used to securely fasten the feeder. These are also to be used when lifting the equipment. The use of a crane or forklift is recommended with a spreader bar. If the equipment must be lifted manually a minimum of two people should lift the equipment.



**WARNING!** – **DANGER!** Do not extend hands into the hopper while the unit is running. The feeder must be installed so a person cannot reach into the hopper. This can be done by using a permanently mounted wire mesh over the top, or installing the optional cover. The operator should always lockout and tagout the equipment before servicing.

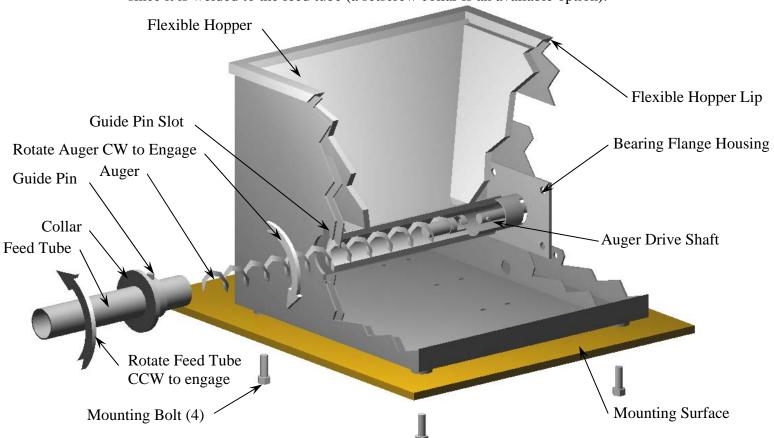
## Section 1.00 Safety



- WARNING! DANGER! Follow all local electrical and safety codes as well as the National Electrical Code (NEC) and the Occupational Safety and Health Act (OSHA). Improper wiring or improper grounding could cause serious personal injury or death. Disconnect and lock out all power from the feeder before servicing. Only authorized service technicians should have access to the inside of the control panel. If the control panel has a key it should only be accessible to authorized personnel. Even with the equipment turned off live voltage can be inside the control panel.
- **1.06 WARNING!** The standard feeder is not "explosion-proof". The standard feeder must not be run in an environment where conditions exist that could cause an explosion of dust or gas. Special built explosion proof feeders are available from Tecnetics.
- **1.08** Operate the feeder **only** when all parts and guards are in place. Use caution when touching the exterior of the operating motor. It could be hot enough to cause personal injury.
- **1.09 WARNING!** Excessive loading of the feeder could result in damage to the feeder or personal injury. **Consult a Tecnetics applications engineer** before applying a concentrated or distributed load exceeding 200 lbs (90 kg) on top of the feeder. The feeder is designed to handle heavy loads, if the loads are applied correctly.
- **1.10** All proper WARNINGS and SAFEGUARDS must be included in the application design and properly placed during feeder installation to insure complete operator protection under all automatic start-up conditions.
- 1.11 Equipment should be operated in a dry environment within a temperature range of 40-110 degrees Fahrenheit (4-43 degrees Celsius) and a relative humidity less than 80%. Avoid contact with water unless your equipment has been designated a wash-down unit.
- **1.12** If equipment is to be stored for an extended period of time, lubricate chain, keep equipment in a cool dry area and do not expose the urethane flex hopper to sunlight.

# Section 2.00 Checklist Before Operation

- 2.01 The Tecweigh Volumetric Feeder has components that are selected at the time of sale for specific performance depending on the material type and feed rate. The factory must be consulted before any changes are made during the warranty period. This is also recommended after the warranty period.
- **2.02 CAUTION:** The feeder application should be considered carefully, if stoppage of the material flow could cause any property damage, losses, or personal injury. If any questions exist about an installation, please consult a Tecnetics applications engineer. Heed the safety instructions in Section 1.00.
- **2.03** The operator must always lockout and tagout equipment before cleaning. Be sure the upper edge of the flexible hopper is fully seated down onto the "lip" of the feeder cabinet.
- Slide the auger through the front of the feeder until it stops. Slowly rotate the auger until it engages with the drive shaft, and then push the auger forward slightly more feeling the resistance of the spring. Press the auger into the spring firmly, and turn the auger about 1/4 turn clockwise until it stops, and then release. Finally, verify the auger is locked in place by jerking on it.
  - 2.05 The feed tube is placed through the front of the feeder as shown below. The guide pins are guided through the guide pin slots on the cabinet. Finally, twist the feed tube about 1/4 turn counterclockwise until it stops. The feed tube collar does not require adjustment, since it is welded to the feed tube (a setscrew collar is an available option).





Have an authorized technician connect the line, neutral, and ground wire to control panel for standard 120-volt controls. Connect L1, L2, and ground input wires to the control panel for optional 230-volt controls. Use a minimum 14 AWG wires. Section 8.00 has the schematics and diagrams necessary to wire your equipment.

# Section 3.00 Operation, Calibration, and Maintenance

- 3.01 A three position green pushbutton switch, start/enable/stop is mounted on the control panel. To START the feeder, PULL the GREEN knob two positions toward you, and then release it. The switch on the control panel will be illuminated when the feeder is running. Verify that the auger is rotating counter clockwise when unit is powered up. See Section 5.00 for troubleshooting suggestions if feeder will not run.
- **3.02** To STOP the feeder, PUSH the GREEN knob in completely.
- 3.03 The speed can be adjusted from 0 to 999 as required using the three-digit SPEED CONTROL selector (see figures on page 6). The speed range is linear (i.e. at 500 the feeder will be running at 50% speed). If the feeder control contains optional remote analog speed control capabilities, an "AUTO-MANUAL" selector switch will be present. In the "AUTO" position the feeder speed can be controlled by a 4-20ma or 0-10 VDC input signal. In the "MANUAL" position the three-digit speed control selector described above can control the feeder speed.
- 3.04 The speed, size of auger, and material will affect the feed rate. Calibration of the feeder must be done with the actual material that will be used. The calibration process:
  - a. Run the feeder for approximately five minutes prior to calibration.
  - b. Set the speed control selector at a setting of 500 and collect several one (1) minute samples. Determine the net weight of each sample.
  - c. Obtain the average weight of samples by adding the net weight of all samples taken and dividing by the number of samples taken. This is the average feed rate per minute. Multiply the average feed rate per minute by 60 to obtain the average fed rate per hour at the 500 setting.
  - d. On the calibration graph located on page 7, plot the average feed rate in pounds or kilograms per hour at the 500 setting. Repeat the same procedure at 100 and 900 settings. Draw a line connecting the three points plotted at 100, 500, and 900. If the line is straight, it can be used to determine feed rates at all other speed control settings on the line. If the line is a curve, it can help you determine the speed control setting for a desired feed rate. However, actual material test samples should be taken to determine the actual feed rate at a particular speed control setting.
- 3.05 The feeder can be easily disassembled for cleaning and inspection. The operator must always lockout and tagout equipment before cleaning.
  - a. Remove the feed tube by twisting it clockwise, causing it to unlock.
  - b. Remove the auger by pushing it firmly in and then twisting it counter-clockwise 1/4 turn until it stops. Then pull the auger towards yourself with a slight jerking motion. On food grade models loosen the auger drive bolt, and remove the auger drive shaft, then remove sanitary clamp, and remove auger drive housing and seal for cleaning and inspection
  - c. Free the flexible hopper from the bearing flange housing and lift the hopper out of the feeder. The chassis lifts out of the cabinet. Care must be used with the electrical connections when lifting the chassis from the cabinet.
  - d. All roller bearings are sealed and do not need to be greased. The drive chain and rodend bearings should be lubricated annually with multi-purpose grease. Reverse the above procedures to reinstall the parts.

### Section 3.00

## **Operating and Calibrating the Feeder**

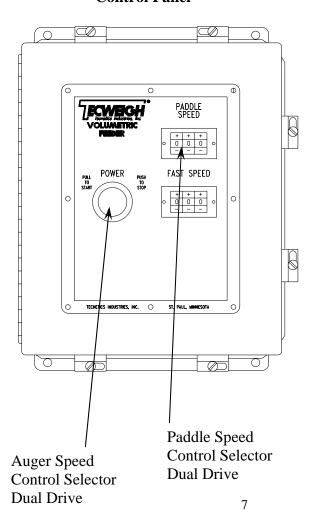
- 3.06 The motor is protected against overload by the control panel circuitry and a fuse. Every effort is made at the time of sale to determine the conditions that might lead to a motor overload. In general, higher speeds (particularly high ratios in the gearbox and drive train) and heavy materials will require more power.
- 3.07 A high temperature environment limits the motor horsepower output. If temperatures encountered are significantly higher than ambient, contact a factory representative.
- **3.08** The control panels shown below are examples, your equipment may have a separate emergency stop. See Section 8.00 of the manual for a schematic(s) and drawings specific to your system.
- 3.09 Dual drive feeders also have a paddle three digit speed control selector (shown below). Increase the paddle speed if material is bridging or rat-holing in hopper. Reduce the paddle speed if material is compacting around the auger.

### Single Drive Volumetric Feeder Control Panel

# TECHTICS NO STRES, INC. O ST. PAUL. NO SSORIA Auger and Paddle Speed Control Selector Single Drive

Three-position (Stop/Enable/Start) Illuminated Mushroom Head Push Pull Switch

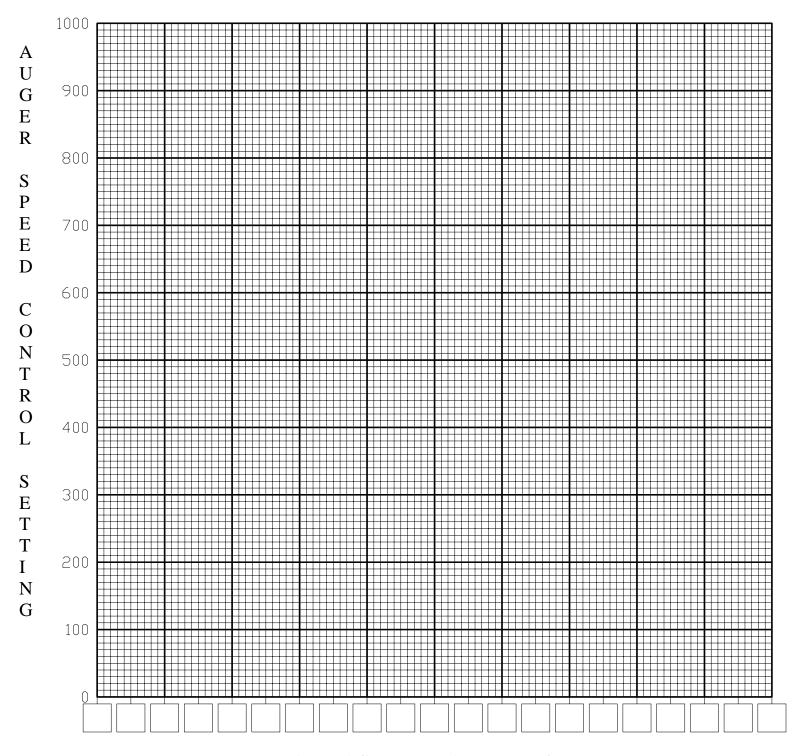
### Dual Drive Volumetric Feeder Control Panel



# Section 3.00 Operating and Calibrating the Feeder

### **CALIBRATION GRAPH**

Auger Diameter		Feeder Serial No
Feeder Drive		Calibrated By
Material Fed		Date
Feed Rate in	per	

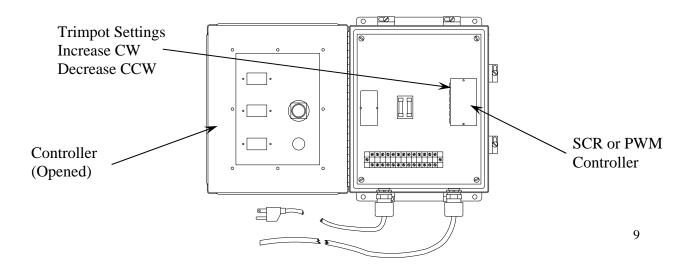


# Section 4.00 SCR/PWM Controller Adjustments



A standard solid state SCR or PWM controller is provided with every standard model feeder for controlling the speed of the DC motor(s). The controller provides adjustments for motor speed limits, acceleration, deceleration, torque, and IR compensation. These adjustments should only be done by an authorized service technician.

- **4.02** All SCR/PWM speed control boards are pre-set at the factory for optimum performance; however, field adjustments can be made on the speed control board by using a small, non-metallic screwdriver on the appropriately labeled trimpot. The internal adjustments are:
  - a. **MIN SPD** Minimum Speed– This sets the minimum DC voltage (minimum speed) for the motor. It is typically set where the auger just begins to turn at a speed setting of "000".
  - b. **MAX SPD** Maximum Speed This sets the maximum DC voltage (maximum speed) for the motor. It is typically set at 90 VDC, at a speed setting of "999" (180 VDC for 230-volt controls).
  - c. **TORQUE** Torque Limit **This is set at the factory**. This protects the SCR/PWM control board and motor against overloads. It limits the amount of current the motor is allowed to draw from the SCR/PWM speed controller. This setting must be set no more than 120% motor nameplate current. The motor must be stalled and motor current measurements made with an ammeter. If a new SCR/PWM control board, motor, or pot is installed in the field, the unit must be recalibrated or the warranty is voided. Calibration procedures are provided with every replacement board.
  - d. IR COMP IR Compensation The trimpot setting determines the degree to which motor speed is held constant as the motor load changes. This is to be set only at the factory, unless a new board is being installed. Refer to the calibration procedures provided with replacement board for setting instructions.
  - e. **ACCEL Acceleration** Adjusts the amount of time it takes the motor to change speed after adjusting the push button speed control. **This is to be set only at the factory, unless a new board is being installed. Refer to the calibration procedures provided with replacement board for setting instructions.**
  - f. **DECEL Deceleration** Determines the time the motor takes to ramp to a lower speed. This is to be set only at the factory, unless a new board is being installed. Refer to the calibration procedures provided with replacement board for setting instructions.



# **Troubleshooting**

PROBLEM	POSSIBLE CAUSE	SOLUTION
Unit does not operate. No indicator light. No voltage at motor terminals.	No power to the control panel, or fuse blown in the control panel.	Check the power source and control panel fuses.
Unit does not operate. Indicator light is on.	Defective SCR/PWM board. Speed control setting set too low. Motor fuse is blown.	Replace SCR/PWM board. Adjust to higher speed. Replace the fuse.
Unit does not operate. Indicator light is on. There is voltage at motor, but no current draw.	Motor is open-circuited by defective brushes or commutator.	Repair or replace the motor.
Unit does not operate. Indicator light is on and there is high current draw to motor.	Something is jammed and preventing rotation of the motor.	Disconnect power and check the auger and paddles for free movement. Second, check the drive train under the cover. Third, check the gearbox for broken parts.
Motor appears to operate, but the auger and/or paddles do not operate.	Something is broken in the drive train.	Disconnect power and check the auger and paddles. Second, check the drive train housing for a broken roller chain, sprocket, or sprocket to shaft connection. Third, check the gear case.
Intermittent rotation of auger and/or paddles.	Shaft sprocket connection slipping. Motor brushes worn. Commutator worn. Damaged gear in gear case.	Repair defective item. SCR/PWM could be defective, repair or replace.
The circuit breaker or fuse at the 120 volt (230 volt) source continually trips/blows.	Direct short in the control panel.	Disconnect power and check the components in the control panel for shorts to ground, and repair as necessary.
Feeder does not make desired rate.	Change in material or bulk density.	Consult applications engineer for a possible change in auger and feed tube.
Material bridges across the flexible hopper.	Increased moisture content in material. Insufficient paddle agitation.	Increase paddle amplitude on single drive feeders. Increase paddle speed on dual drive feeders.
Auger breaks.	Foreign objects caught in auger. Highly cohesive material.	Check feeder for foreign objects. Consult Tecnetics about adding a center rod to the auger for increased strength.
Material flows erratically out of feed tube.	Motor or SCR/PWM board failure.	Test and replace failed components.
Auger stalls and fuse doesn't blow.	Current limit set too low.	Adjust current limit as specified in Section 4.00

# Section 6.00 Technical Data

Tecnetics Industries, Incorporated, reserves the right to make changes or improvements in its products without notice.

**6.01** Electrical Requirements: 5 Series–120/240 VAC, 50/60 Single Phase 3/1.5 amps

**6.02** Motor/RPM Selection: 5 Series–1/4 HP TENV 230VAC 1750 RPM or 90VDC

11:1 ratio reducer

**6.03** Control: Variable Speed SCR, PWM, or AC Variable Frequency

Drive (VFD)

**6.04** Contact Materials: Hopper – 1/4" (6 mm) Thick Flexible Polyurethane

Auger – 304 Stainless Steel (standard) Feed tube – 304 Stainless Steel (standard)

**6.05** Non-Contact Materials: S Style – 10 Gauge 304 Stainless Steel Cabinet

16 Gauge 304 Stainless Steel Hopper

**6.06** Feeder Hopper Capacity: 5 Series – 0.5 Cubic Feet (.014 Cubic Meter)

**6.07** Agitation: Two 304 Stainless Steel Paddles for massaging flexible

Hopper side walls.

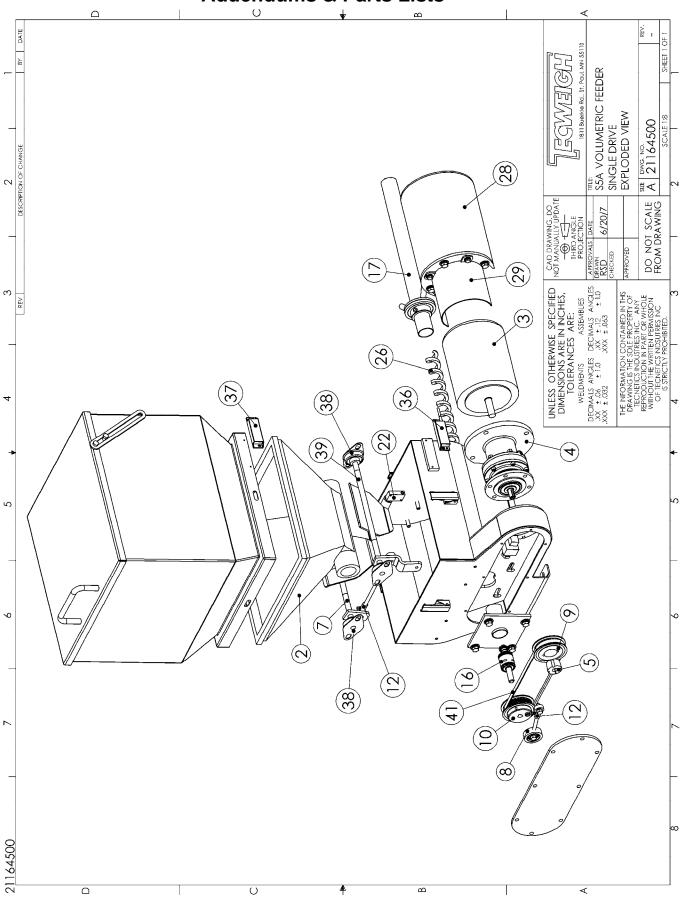
**6.08** Weight: 5 Series Single Drive = 120 pounds (50 Kg)

**6.09** Auger Size and Rates: From 5 RPM to 190 RPM

**Note:** These are normal rates given under ideal conditions. Rates will vary depending on bulk density, moisture content, and material.

0.25" ( 6 mm) with Centerrod	0.0075 – 0.06 Cubic Feet (212 – 1699 Cubic Cm) per Hour
0.38" (10 mm) with Centerrod	0.0260 – 0.21 Cubic Feet (736 – 5947 Cubic Cm) per Hour
0.50" (13 mm) with Centerrod	0.0600 – 0.48 Cubic Feet (.002 – .014 Cubic M) per Hour
0.50" ( 13 mm)	0.0680 – 0.55 Cubic Feet (.002 – .016 Cubic M) per Hour
0.75" (19 mm) with Centerrod	0.2000 – 1.60 Cubic Feet (.006 – .045 Cubic M) per Hour
0.75" ( 19 mm)	0.2300 – 1.84 Cubic Feet (.007 – .052 Cubic M) per Hour
1.00" (25 mm) with Centerrod	0.4100 – 3.27 Cubic Feet (.012 – .093 Cubic M) per Hour
1.00" ( 25 mm)	0.5500 – 4.36 Cubic Feet (.016 – .123 Cubic M) per Hour
1.25" (32 mm) with Centerrod	0.9300 – 7.43 Cubic Feet (.026 – .210 Cubic M) per Hour
1.25" ( 32 mm)	1.0700 – 8.52 Cubic Feet (.030 – .241 Cubic M) per Hour

# Section 7.00 Addendums & Parts Lists

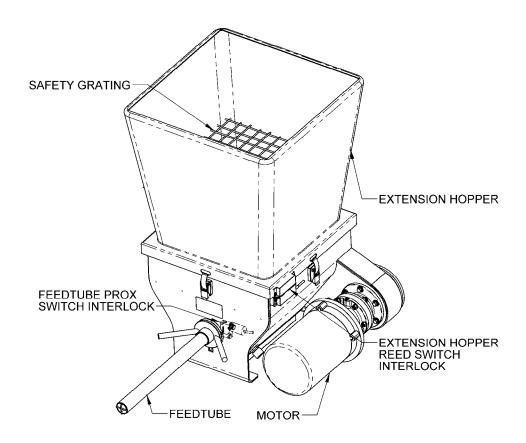


# Section 8.00 Control Features and Schematic Drawings

- **8.01 One Speed** (Standard Feeder) This unit allows the operator to locally power-up and adjust the auger speed (volumetric rate). The three position "POWER" button allows the operator to power up and power down the unit. The three segment digital potentiometer (pot) designates what percentage (0-99%) of full speed the auger and paddles can run. The pot controls an SCR board, which generates a DC voltage output proportional to the pot setting.
- **8.02 Remote Start/Stop** (Standard Feeder) This feature allows a remote device (PLC, Start Switch, etc.) to power up and power down the unit. The remote device must use a two contact operation. One maintained closed for "REMOTE ENABLE/STOP" and one momentary (pulsed) closed for "REMOTE START".
- **8.03 Remote Analog Speed Control** (Optional) A remote analog speed signal from the customer's PLC controls the auger speed instead of the potentiometer. The input signal can either be a 4-20ma or a 0-10 VDC signal. This input signal is isolated by an input board and then fed to the SCR board. A "SPEED SOURCE" selector switch designates which speed input the SCR will read. If the switch is in "AUTO" the remote analog source provides the speed control. If the switch is in the "MANUAL" position, the potentiometer provides the speed control.
- 8.04 Two Speed Control (Optional) By adding a "SLOW" speed pot and a means to switch between it and the "FAST" speed pot, remote two speed control is possible. This feature allows the system to be run at the "FAST" speed pot setting for the majority of a batch and then switched to the "SLOW" speed setting to dribble in the remaining portion. This method allows greater batch accuracy. A set of dry contacts from the customer's PLC or batching unit is needed to remotely switch from the "FAST" to the "SLOW" speed potentiometers. Open contact would be "FAST" and closed contact would be "SLOW".
- **8.05 Paddle Speed Control** (Optional) A separate "PADDLE SPEED" potentiometer and SCR board are added to allow local paddle agitation speed control. The pot allows the paddle agitation speed to be set between 0-99% of maximum. The potentiometer provides a speed signal to the SCR board, which in turn supplies a proportional DC voltage to the paddle motor.

# Section 9.00 CE Compliance

- **9.01** S5A units supplied with CE label and Declaration of Compliance include CE labeled motor, safety grating in the extension hopper, extension hopper interlock and feed tube interlock.
- **9.02 Motor -** The inverter(s) selected by the customer to drive the feeder motor(s) must be CE labeled. The motor and customer supplied inverter drive must be installed in a way that meets or exceeds the inverter drive manufacturer's recommendations for installations requiring CE compliance.
- **9.03 Safety grating -** The safety grating supplied in the extension hopper will be welded in permanent or require tools for removal. If the safety grate supplied is removable using tools, it must ALWAYS be replaced before running the feeder. Tag out/lock out procedures MUST be followed if the safety grate is removed while the hopper is mounted on the feeder cabinet.
- **9.04 Extension hopper interlock** A coded magnetic reed switch is supplied between the extension hopper and the feeder cabinet. This switch MUST be wired into the customer supplied controller's safety circuit to shut the equipment down if the extension hopper is removed. See the wiring diagram below.
- **9.05 Feed tube interlock** A proximity switch is supplied that confirms the feed tube is in place while the unit is operating. This switch MUST be wired into the customer supplied controller's safety circuit to shut the equipment down if the feed tube is removed. The proximity switch requires 10-30 VDC @ 200 ma max. See the wiring diagram on the following page.



# Section 9.00 **CE Compliance** ပ Ω R > 1 SHEET 1 or 1 CE SW ASSYS 21180900 1 DESCRIPTION THIS DOCUMENT IS THE PROPERTY OF TECHTICS INDUSTRIES. IT MAY NOT BE LESD, COPIED OR DISCLOSE TO OTHERS INTERNATION INDUSTRIES. FILE LOCATION VASCHEHATICSVZ180900.DVG SWITCHES MUST BE CONNECTED TO CLIENT'S CONTROLS TO MEET CE M 30 VDC MAX. 200 MA MAX. 10-30 VDC BROWN (LDAD) BLACK BLUE GRAY $\widehat{\pm}$ 0 2 CONNECTOR BLK BRN BLU 9 Q W EXTENSION HOPPER SAFETY SWITCH (108661, 108662) TURCK INDUCTIVE SENSOR (107325) (MOUNTED AT FEED TUBE> 21180900

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# WARRANTY & SERVICE POLICY TECNETICS VOLUMETRIC FEEDERS

### Statement of Limited Warranty - Tecnetics Industries, Inc.

Subject to the terms and conditions as stated herein, Tecnetics Industries, Inc. (hereafter referred to as Tecnetics) warrants its equipment to be free from defects in material and factory workmanship for a period of one year from the date of installation or eighteen months after shipment, whichever comes first, except for Flex Feed<sup>TM</sup> hoppers which carry a five year warranty.

### **Terms and Conditions of Limited Warranty**

This obligation is limited exclusively to defective original equipment or supplied by Tecnetics and is subject to the inspection and analysis of Tecnetics to conclusively identify or confirm the nature and cause of failure.

During the product warranty period, defective components, mechanical or electrical, will be repaired or replaced, at the discretion and authorization of Tecnetics, providing equipment owner agrees to return the faulty components to the factory, freight prepaid.

Tecnetics is not responsible and will not be held liable for losses, injury or damage caused to persons, or property by reason of improper installation of Tecnetics products, or product.

This warranty is not applicable for expenses either direct or consequential that may arise from the use or failure of these products.

Tecnetics reserves the right to incorporate improvements in material and design of the products without notice and is not obligated to incorporate the same improvements in equipment previously manufactured.

Tecnetics shall not be obligated under any warranty different from its warranty as set forth herein. The Tecnetics warranty is limited to the initial customer and initial installation and is not intended to inure to the benefit of a secondary owner in the event of resale or subsequent installation.

### **Conditions Which Void Limited Warranty**

This warranty shall not apply to equipment which:

- A) Has had repairs or modification not authorized by Tecnetics which has affected the performance or reliability.
- B) Has been subject to misuse, negligent handling, improper installation, accident, damage by fire, water, submersion, or an act of God.
- C) Has had serial numbers altered, defaced or removed.

### **Freight Carrier Damage**

Claims for equipment damaged in transit must be referred to the freight carrier. Visible damage should be reported immediately, and concealed damages as soon as possible, in any case, within fifteen (15) days of receipt of shipment, in accordance with freight carrier regulations.

THE FOREGOING IS IN LIEU OF ALL OTHER WARRANTIES, EXPRESS OR IMPLIED, INCLUDING ANY WARRANTIES THAT EXTEND BEYOND THE DESCRIPTION OF THE PRODUCT. THIS WARRANTY STATEMENT SETS FORTH THE EXTENT OF OUR LIABILITY FOR BREACH OF ANY WARRANTY OR DEFICIENCY IN CONNECTION WITH THE SALE OR USE OF THE PRODUCT. IT IS UNDERSTOOD THAT WE WILL NOT BE LIABLE FOR CONSEQUENTIAL DAMAGES OF ANY NATURE, INCLUDING BUT NOT LIMITED TO, LOSS OR PROFITS, DELAYS OR EXPENSES WHETHER BASED ON TORT OR CONTRACT.